

Lecture 3

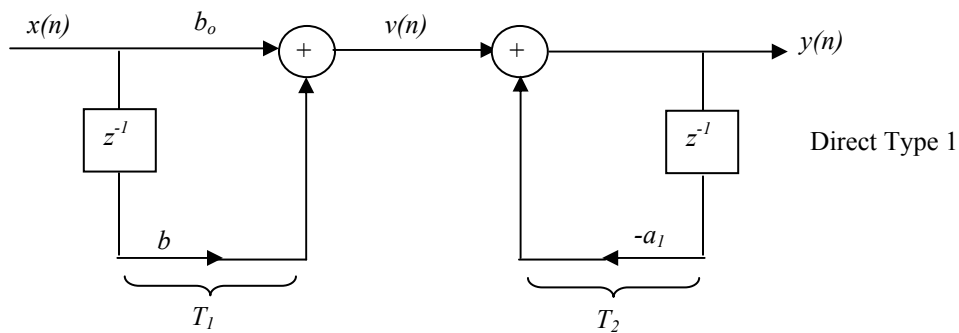
Implementation of Discrete-Time Systems

Lets start with 1st order system:

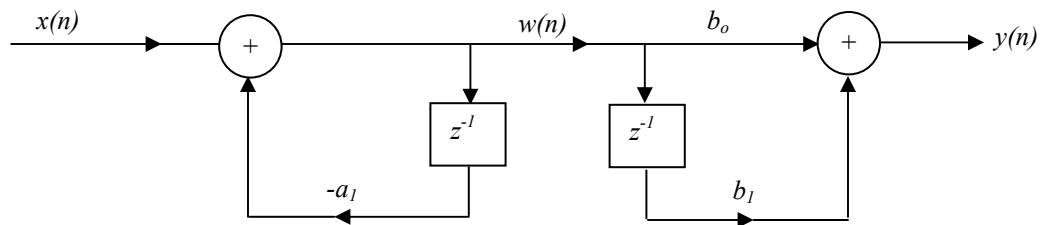
$$y(n) = -a_1 y(n-1) + b_0 x(n) + b_1 x(n-1) \text{ or } \sum_{k=0}^M a_k y(n-k) = \sum_{k=0}^N b_k x(n-k)$$

This can be considered as $v(n) = b_0 x(n) + b_1 x(n-1)$ and

$$y(n) = a_1 y(n-1) + v(n)$$



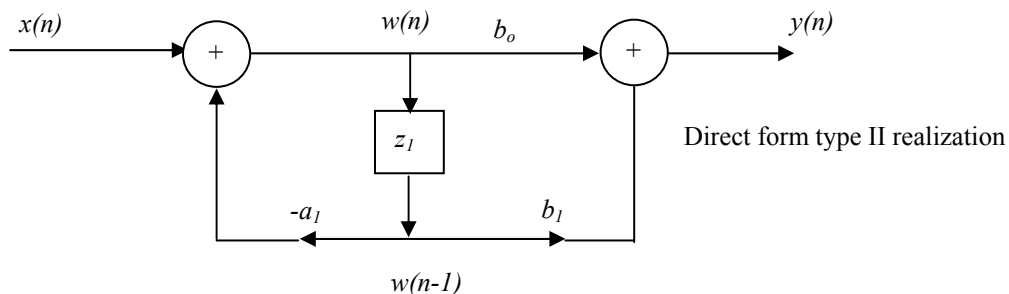
But for the LTI system, we can interchange the order and write $T = T_2 \bullet T_1 = T_1 \bullet T_2$



From this figure we can write: $w(n) = -a_1 w(n-1) + x(n)$

$$y(n) = b_0 w(n) + b_1 w(n-1)$$

Now we can combine the two delays and get



and $|r_{xx}(\ell)| \leq r_{xx}(0) = E_x$

Normalized auto or cross correlation:

$$\rho_{xx}(\ell) = \frac{r_{xx}(\ell)}{r_{xx}(0)} \leq 1 \quad \rho_{xy}(\ell) = \frac{r_{xy}(\ell)}{\sqrt{r_{xx}(0)r_{yy}(0)}} \leq 1$$

For periodic signals, the correlation function is defined in one period:

$$r_{xy}(\ell) = \lim_{M \rightarrow \infty} \frac{1}{2M+1} \sum_{n=-M}^M x(n)y(n-\ell),$$

where M is the number of observed samples.

If x and y are both periodic with period N , then

$$r_{xy}(\ell) = \frac{1}{N} \sum_{n=0}^{N-1} x(n)y(n-\ell) \Rightarrow \text{correlation is also a periodic sequence with period } N.$$

Question: Consider a signal $x(n) = \cos 2\pi\left(\frac{1}{3}\right)n$ for 100 samples. Its autocorrelation is periodic with the same $\frac{1}{3}$ frequency but its magnitude decreases as ℓ increases. Why?

Answer: Because we have a finite set of data recorded at M samples. So many of the products of $x(n)x(n-\ell)$ are zero when ℓ increases. Therefore, we should avoid computing $r_{xx}(\ell)$ for large lags, say $\ell > M/2$.

A Practical Application at Usage of Autocorrelation Function

Lets say we have a signal with unknown period N and it is corrupted by additive white noise. Then $r_{xx}(\ell)$ can be used to detect its periodicity $y(n) = x(n) + w(n)$.

$$\begin{aligned} r_{yy}(\ell) &= \frac{1}{M} \sum_{n=0}^{M-1} y(n)y(n-\ell) \quad M \gg N \\ &= \frac{1}{M} \sum_{n=0}^{M-1} [x(n) + w(n)][x(n-\ell) + w(n-\ell)] \\ &= \frac{1}{M} \sum_{n=0}^{M-1} [x(n)x(n-\ell) + x(n)w(n-\ell) + w(n)x(n-\ell) + w(n)w(n-\ell)] \\ &= r_{xx}(\ell) + r_{ww}(\ell) + r_{xw}(\ell) + r_{wx}(\ell) \end{aligned}$$

If $w(n)$ is a white noise then it has value only at lag 0 (only $r_{ww}(0)$ is not zero). r_{xw} and r_{wx} are almost zero and therefore, only $r_{xx}(\ell)$ is showing some peaks for every period.

Solving Difference Equation With MatLab

Example

$$y(n) - y(n-1) + 0.9 y(n-2) = x(n) \quad \forall n \sum_{K=0}^M a_K y(n-k) = \sum_o^N b_K x(n-1)$$

- Calculate and plot $h(n)$ for $n = -20, \dots, 120$
- Calculate and plot the unit step response
- Is the system stable?

Solution

a) $a = [1, -1, 0.9]$, $b = [1]$;

$$n = [-20 : 120];$$

$$n_o = 0; x = [(n - n_o) = 0]; \quad \% \text{ creates impulse at } 0$$

$$h = \text{filter}(b, a, x);$$

$$\text{stem}(n, h); \text{title}(' \text{Impulse Response} '); \text{ylabel}(' h(n) ');$$

$$\text{xlabel}(' n ');$$

b) $x = [(n - n_o) \geq 0];$

$$s = \text{filter}(b, a, x);$$

$$\text{stem}(n, s) \text{ title}(' \text{Unit Step Response} ');$$

C) As can be seen $h(n)$ is decaying $\rightarrow \sum |h(n)|$ can be determined by

$$\text{sum}(\text{abs}(h)) = 14.87 < \infty$$

Alternative method:

$$z = \text{roots}(a); \text{ (characteristic roots)}$$

$$\text{magz} = \text{abs}(z)$$

$$\text{magz} = \begin{cases} 0.9487 \\ 0.9487 \end{cases} < 1 \rightarrow \text{stable}$$

Z-Transform (Chapter 3)

Z-Transform plays the same role as the Laplace Transform for CT signals. It is defined

$$\text{as } x(z) = \sum_{n=-\infty}^{+\infty} x(n)z^{-n} \quad x(n) \xleftrightarrow{\text{Z}} x(z)$$

$x(z)$ exists only for values that this power series converges.

The Region of Convergence (ROC) is the set of all values of z , where $x(z)$ attains a finite value.

Example 1

$$x_1(n) = \{1, 2, 5, 7, 0, 1\}$$

↑

$$X_1(z) = 1 + 2z^{-1} + 5z^{-2} + 7z^{-3} + z^{-5}$$

ROC: entire z plane except $z = 0$

$$x_2(n) = \{1, 2, 5, 7, 0, 1\}$$

↑

$$X_2(z) = z^2 + 2z + 5 + 7z^{-1} + z^{-3}$$

ROC entire z plane except $z = 0, \infty$

Conclusion 1– In order to uniquely define $x(n)$ from $x(z)$, we have to know ROC.

Conclusion 2 – For a finite duration signal, ROC = entire z plane except $z = 0/\infty$

Exponential Signals

Example 1

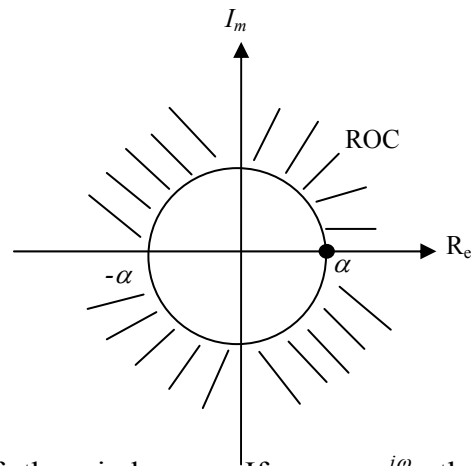
$$x(n) = \begin{cases} \alpha^n & n \geq 0 \\ 0 & n < 0 \end{cases}$$

$$X(z) = \sum_{n=0}^{\infty} \alpha^n z^{-n} = \sum_{n=0}^{\infty} (\alpha z^{-1})^n$$

$$\text{If } |\alpha z^{-1}| < 1 \text{ or } |z| > |\alpha|, \text{ then } X(z) = \frac{1}{1 - \alpha z^{-1}}.$$

In general, $z = re^{j\omega} \rightarrow |z| = |r| > |\alpha|$ outside of the circle α . If $z = re^{j\omega}$, then

$$X(z) = \sum_{n=-\infty}^{+\infty} x(n)r^{-n}e^{-j\omega n}.$$



In the ROC of $X(z)$, $|X(z)| < \infty$

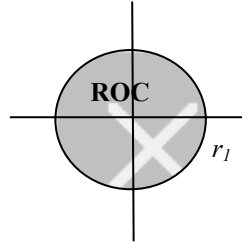
$$\text{But } |X(z)| = \left| \sum_{n=-\infty}^{+\infty} x(n) r^{-n} e^{-j\omega n} \right| \leq \sum_{n=-\infty}^{+\infty} |x(n) e^{-j\omega n} r^{-n}| = \sum_{n=-\infty}^{+\infty} |x(n) r^{-n}| < \infty$$

Therefore, $|x(z)|$ is finite if $x(n)r^{-n}$ is absolutely summable. In order to find the range of r , we rewrite the above as:

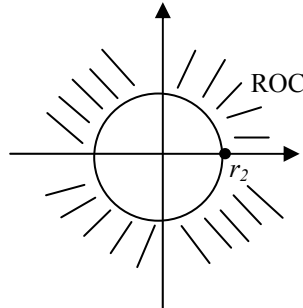
$$|x(z)| \leq \sum_{n=-\infty}^{-1} |x(n) r^{-n}| + \sum_{n=0}^{\infty} \left| \frac{x(n)}{r^n} \right| = \sum_{n=1}^{\infty} |x(-n) r^n| + \sum_{n=0}^{\infty} \left| \frac{x(n)}{r^n} \right|$$

The convergence of the first term means there must exist values of $r_1 < \infty$ such that

$$\sum_{l=1}^{\infty} |x(-n) r_l^n| < \infty$$



The second term implies that there exists values $0 < r_2 < \infty$ that $\sum_{n=0}^{\infty} \left| \frac{x(n)}{r_2^n} \right| < \infty$



Combining the two, therefore ROC is a ring $0 < r_2 < r < r_1 < \infty$. If $r_2 > r_1$, then there is no ROC.

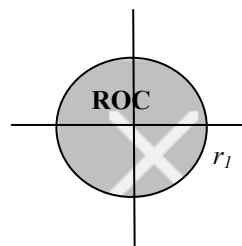
Example 2

$$x(n) = -\alpha^n U(-n-1) = \begin{cases} 0 & n \geq 0 \\ -\alpha^n & n \leq -1 \end{cases}$$

$$X(z) = \sum_{n=-\infty}^{-1} (-\alpha^n) z^{-n} = - \sum_{n=1}^{\infty} (\alpha^{-1} z)^n, \text{ if } |\alpha^{-1} z| < 1 \text{ then } X(z) = \frac{-\alpha^{-1} z}{1 - \alpha^{-1} z} = \frac{1}{1 - \alpha z^{-1}}$$

As can be seen, $X(z)$ of this example is the same as the one in Example 1, but their ROC

are different. Here, $|\alpha^{-1}z| < 1 \rightarrow \frac{|z|}{|\alpha|} < 1 \rightarrow |z| < |\alpha|$



Comparing Example 1 and 2:

- 1) We have to know ROC in order to define $x(n)$ from $X(z)$ uniquely.
- 2) ROC of a causal signal is the exterior of a circle of some radius while the ROC of a non-causal signal is the interior of a circle.

Example 3

$$x(n) = \alpha^n u(n) + \beta^n U(-n-1)$$

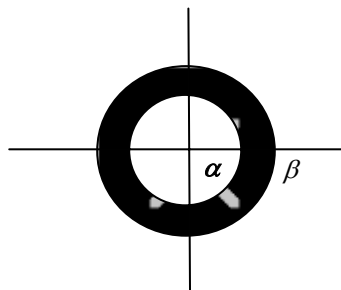
$$\downarrow z$$

$$X(z) = \frac{1}{1 - \alpha z^{-1}} - \frac{1}{1 - \beta z^{-1}}$$

but each of these terms exists if

$$|z| > |\alpha| \text{ and } |z| < |\beta|$$

Therefore, $X(z)$ exists if $\exists \alpha$ and β such that $|\alpha| < |\beta|$. Then $\alpha < |z| < \beta$ is the ROC



Conclusion

ROC for an infinite two-sided duration signal is a ring.

Read the summary on page 159 of the textbook.